Combined Forecast and Quantile Regression for Wind Power Prediction

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1 Introduction

This report will discuss probabilistic forecast of wind-power production. The focus will be how different meteorological forecasts can be combined into a prediction of the distribution of future wind-power production. The combined forecasts are constructed as described in [8], the basic model is

$$p_c = w_0 + \sum_{j=1}^{J} w_j p_j,$$
 (1)

where $\sum_{j=1}^{J} w_j = 1$ and p_j is the predicted power based on forecast j. The weights w_j are based on the correlation structure between the p_j 's. The scope of this report is to examine the residuals from the combined forecast to give a probabilistic characterization of these residuals. The methodology will be quantile regression as presented by Koenker in [2], and the time-adaptive method presented in [5], [6] and [7].

Section 2 gives a short presentation of quantile regression and how nonlinear relations can be modelled in a linear quantile regression setting. Section 3 presents the data used in the analysis. An evaluation of probabilistic models is somewhat more complicated than the evaluation of point forecasts. The performance of quantile models is therefore discussed in Section 4. Section 5 presents some static models for the combined forecast. Finally Section 6 presents some time-adaptive quantile regression models.

2 Quantile Regression

The quantile regression models presented in [2] are linear regression models. If τ denotes a quantile, then given a vector of explanatory variables \mathbf{x}_t the regression quantile is

$$Q_{\tau}(\mathbf{x}_t) = \mathbf{x}_t^T \boldsymbol{\beta}.$$
 (2)

The asymmetrical and piecewise linear loss function for quantile regression is defined as

$$\rho_{\tau}(r) = \begin{cases} \tau r & \text{for } r \ge 0\\ (\tau - 1)r & \text{for } r < 0, \end{cases}$$
(3)

with $r_t = Q_{\tau}(\mathbf{x}_t) - y_t$, minimizing the sum of the r_t 's gives the τ quantile. The estimate $\hat{\boldsymbol{\beta}}$ of $\boldsymbol{\beta}$ given N observations is

$$\hat{\boldsymbol{\beta}} = \arg\min_{\boldsymbol{\beta}} \sum_{i=1}^{N} \rho_{\tau}(r_i).$$
(4)

In this presentation the regressors are (functions of) meteorological forecasts, horizons and the weights defined above. The focus will be on the 25%and 75% quantile, but quantile regression can be performed for any quantile in question.

2.1 Non-Linear Relations with Linear Regression

Quantiles of the residuals as functions of forecasted wind-power are not expected to be linear functions (see [4]). To apply the setting of linear quantile regression, these unknown functions are approximated by linear combinations of spline basis functions (see e.g. [1]). These are further combined in an additive model, such that the model structure becomes

$$\hat{Q}_{\tau}(x_1, ..., x_K) = \hat{\alpha}(\tau) + \sum_{j=1}^K \hat{f}_j(x_j),$$
(5)

where the functions \hat{f}_j are either linear combinations of natural spline basis functions or linear functions, and x_j is the explanatory variables. The functions must be fixed somehow (e.g. by $\hat{f}_j(0) = 0$) to ensure uniqueness of the parameters in the model. This is done by forcing all spline basis functions to be zero at the left-most boundary knot. The term $\hat{\alpha}$ is the common intercept for the combined model.

As mentioned above, the functions f_j are approximated by linear combinations of spline basis functions

$$\hat{f}_{j}(x_{j}) = \sum_{l=1}^{n_{j}} b_{j,l}(x_{j})\hat{\beta}_{j,l},$$
(6)

where $b_{j,l}$ is spline basis function number l for the explanatory variable x_j and $\hat{\beta}_{j,l}$ is the coefficient to be estimated. With this \hat{Q} is a linear model in the $b_{j,l}$'s. In addition to the linear regression, we will present some results from time-adaptive quantile regression, i.e. models where $\hat{\beta}_{j,l}$ is replaced by $\hat{\beta}_{j,l,t}$.

3 The Data

The data set consists of hourly measurements of power production from Klim wind-power plant, the predicted power from WPPT (see [3] and [4]) based on three different weather forecasting systems, and the combined forecast. The prediction horizons are between 1 and 24 hours. There are 7272 data points in the data set, spanning the period from February 2nd 2003 to December 12th 2003. For the analysis of the static models the dataset is divided into two parts, a training set and a test set of approximately equal size. The training set has 3648 data points and spans the period from February 2nd 2003 to July 4th 2003. The test set is the remaining data points.

The explanatory variables in the data set are the horizon, the combined forecast and the three different forecasts used by the combined forecast. The forecasts based on different meteorological data are highly correlated and of course these are also correlated with the combined forecast. The objective is to model the uncertainty as a function the combined forecast and some function of the three individual forecasts. The explanatory variables are denoted by

hor: The prediction horizon from the meteorological data

- p_c : The combined forecast based on the three different meteorological forecasts see (1)
- p_{DWD} : Predicted power based on the meteorological forecast from "Deutscher Wetterdienst"
- $p_{HIR}:$ Predicted power based on the meteorological forecast from "DMI-HIRLAM"
- p_{MM5} : Predicted power based on the meteorological forecast from "MM5"

4 The Performance of Quantiles

The problem of providing performance measures for quantiles is not easy and there does not exist any generally accepted measure of the performance of quantiles. In the following a number of different performance measures is presented. These performance measures are discussed in [9] and [5]. The performance measures presented here should all be considered on a test set.

4.1 Reliability

The reliability is simply the relative number of observations below the quantile curve. The reliability of a good model is close to the required probability, but it is not clear what "close" means in absolute terms. [9] presents different measures of quantiles and suggests that reliability should always be considered before any other performance is considered.

4.2 Skill Score

The objective function for quantile regression is also a performance parameter that will be considered. As shown in [9] show that this is actually a skill score. The loss function for a quantile is the skill score for this quantile and the sum of two symmetric (around 50%) quantiles is a skill score for this interval. The skill score for an interval gives one number and is therefore practical for comparing different models. This number should be small.

4.3 Reliability Distance and Local Reliability

In addition to reliability, the reliability distance $d_q(x_j; \tau) = d(q(y; \tau, w))$ as defined in [5] will also be considered. w is a smoothing parameter and will be set to 0.1 in the presentation. Reliability distance is a performance parameter based on local reliability, also defined in [5]. The reliability distance basically measures the distance between reliability as a function of some variable and the required reliability. Reliability distance is one number while local reliability is a function (see Figures 7 and 8). The reliability distance is considered for the combined forecast, the prediction horizon, and time; In the report it is considered as $d_q(x_j)^2 = d_q(x_j, 0.25)^2 + d_q(x_j, 0.75)^2$.

4.4 Crossings

Quantiles are fitted individually and crossings between quantile curves can (and will) therefore occur. The number of crossings ($\sum I(IQR < 0)$, with IQR=Inter Quantile Range, i.e $IQR = Q_{0.75} - Q_{0.25}$) on the test set is considered as a performance parameter. In addition the mean (E(IQR|IQR < 0)) and maximum size min(IQR) of these crossings is considered. These numbers should be as small as possible.

4.5 Sharpness

Sharpness is a measure that tells how far quantiles are separated, and given that other performance parameters are acceptable, this should be small. Two different measures are used here, namely the mean of IQR and the median (\tilde{E}) of IQR. Undesirable crossings will contribute positively to sharpness, and therefore only IRQ's larger than zero are considered for sharpness.

4.6 Resolution

Resolution measures how well a model distinguishes between different situations. This is given by measures that award variation in IQR. Here, two measures are used, namely the standard deviation of IQR and the Median Absolute Deviation (MAD), i.e. the median of the absolute deviation from the median, multiplied by 1.44826 for normal consistency. Only IQR's larger than zero are considered.

5 Static Quantile Models

The assumption is that the combined forecast is the most important explanatory variable. In addition we will examine how the forecasts which form the combined forecast can contribute to the model. When comparing models in this study, the skill score for the interval will be considered the most important performance parameter, but as the discussion about the performance of quantiles has yet to be resolved, we will present other performance parameters as well.

5.1 Models with a Risk Index

As a first hypothesis the quantiles are modeled as

$$Q_{\tau}(p_c, r_m, hor) = \alpha(\tau) + f_1(p_c) + f_2(r_m) + f_3(hor),$$
(7)

where r_m is a risk index defined as

$$r_m^2 = \frac{1}{3} \sum_{i=j}^3 (p_j - \overline{p})^2,$$
(8)



Figure 1: The figure shows histograms of the combined forecast and the risk index calculated by (8). Notice that there are very few observations with high values of the risk index.

and the p_j 's are the three forecasts described above. Figure 1 shows histograms of the combined forecast and the risk index defined above. The figure illustrates that there are very few observations with high values of the risk index. This means that the model is expected to perform poorly in this region.

Figure 2 top row shows the model defined in (7) with 10 degrees of freedom in each direction. The knots for the spline basis functions are placed at 10% quantiles of observed data, and are marked with the rugs on the first axis. The function in the direction of the combined forecast behaves as expected, with large uncertainties for moderate values of predicted power, and smaller uncertainties for small or very large values of predicted power. The curves in the direction of the risk index show large distance between the two quantiles for large values of risk index. This is what would be expected, but the curves only vary in areas where there are very few data and the quality of the estimates is questionable in this region. The horizon does not seem to explain any variation in the data and will not be considered further.

Table 1 gives the performance of five different models based on the com-



Figure 2: The figure shows the effects of different components on some of the additive models presented in Table 1.

bined forecast and the risk index defined in (8). Three of these are displayed in Figure 2. The two bottom rows in Figure 2 show models without horizon and with only 5 knots in the direction of the combined forecast. The curve in the direction of the combined forecast shows the same qualitative behavior as with 10 knots. The most significant difference is that the difference between the quantiles is much larger for large forecasted power. This is most likely due to the small number of data points in this region.

The curve in the direction of the risk index behaves quite differently when there are 5 knots instead of 10. For large values of the risk index, this is again due to few data points and the curves should not be trusted in this region. When the risk index is fitted with a linear function, it still shows some dependence, even though this is weak. Table 1 shows that this model (Model 4) gives the best performance in terms of the interval skill score. However, it also shows that the improvement in performance is very small compared to a model with only the combined forecast included. Note also that Model 4 is the only model that performs better than a model without any risk included.

The risk index defined above uses the sqared deviation from the average as the risk factor. Another measure is based on the deviation from the combined forecast. This is calculated by replacing \bar{p} with p_c in (8). The result of this is given in Table 2, while Models 8 and 9 are such models. Further the table gives the result of defining the risk index as the absolute deviation between p_{DWD} and p_{HIR} . The last index is examined because the weather forecasts from MM5 and HIRLAM are known to be highly correlated. The hypothesis is therefore that the deviation between one of these and p_{DWD} alone can explain the uncertainty.

Table 2 shows that the risk index obtained from the deviation from the combined forecast performs better than that obtained with the mean of the forecasts. However an improvement is not seen for all performance parameters. The overall reliability is quite poor for the 25% quantile in all models, while it performs better for the 75% quantile.

The risk index considered so far does not use the fact that the weight changes in time. Therefore it is tested in the following wheter time variation of the weights should be included. The weights sum to one, as they should. They are, however, not all positive. To ensure that the risk index is greater than zero, the risk index is defined such that the weights used for the risk index are proportional to the absolute size of the weights and that they sum

Model	1	2	3	4	5
df hor	10	0	0	0	0
df p_c	10	10	5	5	5
df r_m	10	10	5	1	0
Below 25%	20.7	20.6	21.8	21.4	21.6
Below 75%	73.5	73.6	73.3	74.2	73.6
Between 25% and 75%	53.3	53.5	52.4	54.0	52.5
$ar{ ho}_{0.25}(\mathbf{r})$	458.6	458.6	454.9	455.0	455.0
$ar{ ho}_{0.75}(\mathbf{r})$	556.8	557.6	557.9	556.4	557.0
$\bar{ ho}_{0.25}(\mathbf{r}) + \bar{ ho}_{0.75}(\mathbf{r})$	1015.4	1016.1	1012.8	1011.4	1011.6
$d_q(p_c)$	0.068	0.068	0.070	0.065	0.069
$d_q(hor)$	0.042	0.042	0.037	0.039	0.038
$d_q(t)$	0.037	0.037	0.033	0.036	0.035
$\sum I(IQR < 0)$	42	24	75	53	71
$\min(\mathrm{IQR})$	-9.2	-1.4	-6.4	-8.2	-1.2
E(IQR IQR<0)	-1.4	-0.1	-1.6	-3.5	-0.9
E(IQR IQR > 0)	2317.9	2314.0	2334.2	2324.8	2333.0
$\tilde{E}(IQR IQR > 0)$	2099.0	2093.3	2230.3	2220.8	2226.5
SD(IQR IQR > 0)	1869.0	1889.8	1801.8	1800.6	1800.2
MAD(IQR IQR > 0)	2196.5	2249.6	2520.7	2493.9	2505.6

Table 1: The tables show different performance parameters for different models. Knots are placed at appropriate quantiles of data. The best performer in each row is marked in bold.

Model	6	7	8	9
df p_c	5	5	5	5
df r_{DH}	5	1	0	0
df r_c	0	0	5	1
Below 25%	22.0	20.5	21.5	20.6
Below 75%	73.5	73.8	72.1	74.4
Between 25% and 75%	51.8	53.3	50.5	54.6
$ar{ ho}_{0.25}({f r})$	455.6	454.9	455.3	455.0
$ar{ ho}_{0.75}(\mathbf{r})$	558.6	557.2	555.3	555.8
$\bar{ ho}_{0.25}(\mathbf{r}) + \bar{ ho}_{0.75}(\mathbf{r})$	1014.2	1012.1	1010.6	1010.8
$d_q(p_c)$	0.062	0.068	0.070	0.064
$d_q(hor)$	0.034	0.043	0.044	0.043
$d_q(t)$	0.029	0.041	0.037	0.040
$\sum I(IQR < 0)$	67	48	98	34
$\min(IQR)$	-2.7	-61.9	-16.9	-5.0
E(IQR IQR < 0)	-1.2	-6.6	-7.1	-2.7
E(IQR IQR > 0)	2334.2	2314.4	2353.2	2303.3
$\tilde{E}(IQR IQR>0)$	2241.2	2192.9	2222.4	2198.3
SD(IQR IQR > 0)	1786.7	1803.5	1814.7	1796.7
MAD(IQR IQR > 0)	2495.5	2489.1	2488.5	2493.9

Table 2: The table shows different performance parameters for different models. Knots are placed at appropriate quantiles of data. The best performer in each row is marked in bold.

Model	10	11	12	13
df p_c	5	5	5	5
df $r_{c,w}$	5	1	0	0
df $r_{m,w}$	0	0	5	1
Below 25%	21.8	21.4	22.2	20.9
Below 75%	71.9	75.0	73.3	74.6
Between 25% and 75%	50.8	54.3	52.1	54.6
$ar{ ho}_{0.25}(\mathbf{r})$	456.2	455.0	455.4	455.0
$ar{ ho}_{0.75}({f r})$	557.5	555.6	557.2	556.5
$ar{ ho}_{0.25}(\mathbf{r}) + ar{ ho}_{0.75}(\mathbf{r})$	1013.7	1010.5	1012.6	1011.5
$d_q(p_c)$	0.080	0.065	0.074	0.064
$d_q(hor)$	0.045	0.037	0.036	0.042
$d_q(t)$	0.038	0.036	0.030	0.038
$\sum I(IQR < 0)$	123	31	79	40
$\min(IQR)$	-24.4	-13.3	-14.4	-11.3
E(IQR IQR < 0)	-11.4	-6.4	-2.7	-5.1
E(IQR IQR > 0)	2368.9	2310.2	2350.8	2317.3
$\tilde{E}(IQR IQR > 0)$	2242.9	2171.7	2215.4	2199.5
SD(IQR IQR > 0)	1823.2	1796.2	1843.4	1807.4
MAD(IQR IQR > 0)	2454.4	2450.3	2467.9	2492.3

Table 3: The table shows different performance parameters for different models. Knots are placed at appropriate quantiles of data. The best performer in each row is marked in bold.

to one. This is ensured with the following construction

$$r_{m,w}^2 = \sum_{j=1}^J \frac{|w_j|}{\sum_{j=1}^J |w_j|} (p_j - \bar{p})^2.$$
(9)

A risk index $r_{c,w}$ based on the combined forecast is also constructed, and the result of this is given in Table 3. The result is quite similar to what has been seen so far. There is a small improvement for Model 11, which uses the weighted risk index with the combined forecast. The risk indices considered so far do not seem to give significant improvements compared to a model with only the combined forecast included.

5.2 Other Models

The approach with a risk index did not seem to produce significant improvements compared to models with only the combined forecast included. Models that take the individual forecasts into account are therefore tested in this section.

The first approach is to set up models with the forecasts included as nonlinear functions. Table 4 gives the results for combinations of this, and all models have the combined forecast included. The table shows large improvements for some of the models, especially Model 20 where all the forecasts are included. The forecasts and the combined forecast are connected through (1). Therefore a model that includes all the forecasts might be expected to be too correlated to facilitate a good estimation. This is partly supported by Figure 3 where the change in the function for the combined forecast seems to be compensated for by the three other functions.

The models do not break down completely because the nonlinear functions created by the spline basis functions are defined by the knots, which depends on the observations, and furthermore the weights change over time. If the functions had been linear and the weights constant, then the estimation of Model 20 would not have been possible. In conclusion the performance parameters support Model 20, while Figure 3 suggests that the components are too correlated. The result from Model 20 does, however, support the hypothesis that the forecasts based on different meteorological forecasts contain information on the uncertainty of the combined forecast.

The uncertainty is expected to depend on some kind of deviation between the forecasts. The next step is to let the functions depend on such differences. Models which use the differences between the forecasts and the combined forecast are therefore considered.

Performance parameters for models of this type are given in Table 5. The functions are assumed to be linear. Model 27 performs very well, at least in terms of interval skill score. Figure 4 shows the components of some of the models from Table 5, and it is seen that there are clear trends. However, these are not as we would expect since we have forced a linear function through and we would expect large differences between quantiles for large absolute numbers of the differences. It is also noted that there are large crossings in the plots, but these are not seen in the performance parameter. Again that there are very few observations in these regions of the data.

Model	14	15	16	17	18	19	20
df p_c	5	5	5	5	5	5	5
df p_{DWD}	5	0	0	5	5	0	5
df p_{HIR}	0	5	0	5	0	5	5
df p_{MM5}	0	0	5	0	5	5	5
Below 25%	22.7	22.6	22.6	23.6	24.3	23.6	25.0
Below 75%	74.2	77.2	73.3	77.3	74.6	76.8	76.9
Between 25% and 75%	51.9	55.4	52.5	54.2	51.3	54.1	52.8
$ar{ ho}_{0.25}(\mathbf{r})$	452.8	455.0	458.4	452.5	455.8	455.9	453.4
$ar{ ho}_{0.75}({f r})$	554.8	560.1	558.8	551.1	555.5	557.7	545.2
$\bar{ ho}_{0.25}(\mathbf{r}) + \bar{ ho}_{0.75}(\mathbf{r})$	1007.6	1015.1	1017.1	1003.6	1011.3	1013.7	998.6
$d_q(p_c)$	0.062	0.060	0.069	0.058	0.052	0.054	0.052
$d_q(hor)$	0.031	0.035	0.026	0.032	0.016	0.024	0.024
$d_q(t)$	0.028	0.031	0.030	0.028	0.028	0.025	0.030
$\sum I(IQR < 0)$	55	36	95	32	65	40	38
$\min(IQR)$	-5.0	-3.7	-12.8	-5.7	-13.6	-14.0	-13.5
E(IQR IQR < 0)	-2.8	-2.3	-6.4	-3.5	-4.3	-5.6	-4.7
E(IQR IQR > 0)	2295.2	2417.8	2335.1	2374.3	2278.4	2379.7	2361.4
$\tilde{E}(IQR IQR > 0)$	2177.4	2286.1	2192.1	2268.5	2161.4	2234.4	2237.5
SD(IQR IQR > 0)	1779.8	1887.8	1803.9	1808.8	1737.2	1858.9	1753.2
MAD(IQR IQR > 0)	2352.7	2461.2	2320.3	2363.3	2251.0	2276.8	2267.6

Table 4: The table shows different performance parameters for different models. Knots are placed at appropriate quantiles of data. The best performer in each row is marked in bold.



Figure 3: The figure shows the effects of different components of some of the additive models presented in Table 4.

Model	21	22	23	24	25	26	27
df p_c	5	5	5	5	5	5	5
df $p_c - p_{DWD}$	1	0	0	1	1	0	1
df $p_c - p_{HIR}$	0	1	0	1	0	1	1
df $p_c - p_{MM5}$	0	0	1	0	1	1	1
Below 25%	24.4	29.2	22.6	29.1	25.7	28.6	29.2
Below 75%	75.4	77.4	74.2	77.7	76.5	77.8	78.3
Between 25% and 75%	51.0	48.2	51.6	48.7	50.8	49.2	49.1
$ar{ ho}_{0.25}({f r})$	455.0	454.8	454.9	454.3	454.1	454.5	452.8
$ar{ ho}_{0.75}({f r})$	557.0	557.1	549.3	552.5	549.1	549.7	541.8
$\bar{ ho}_{0.25}(\mathbf{r}) + \bar{ ho}_{0.75}(\mathbf{r})$	1013.0	1011.8	1004.2	1006.8	1003.3	1009.4	994.8
$d_q(p_c)$	0.063	0.094	0.063	0.091	0.064	0.087	0.084
$d_q(\text{hor})$	0.023	0.044	0.028	0.043	0.030	0.042	0.047
$d_q(t)$	0.025	0.041	0.030	0.041	0.038	0.040	0.049
$\sum I(IQR < 0)$	34	27	51	20	15	20	13
$\min(IQR)$	-9.4	-3.2	-3.2	-11.3	-6.5	-7.1	-16.7
E(IQR IQR < 0)	-5.3	-2.5	-2.3	-6.2	-4.5	-4.0	-7.4
E(IQR IQR > 0)	2326.0	2402.8	2278.9	2375.9	2335.3	2392.6	2365.7
$\tilde{E}(IQR IQR > 0)$	2169.8	2197.5	2170.7	2203.1	2153.6	2188.0	2188.2
SD(IQR IQR > 0)	1804.2	1887.8	1740.5	1837.3	1759.6	1858.6	1748.6
MAD(IQR IQR > 0)	2431.1	2518.5	2378.4	2467.8	2273.6	2441.0	2281.3

Table 5: The table shows different performance parameters for different models. Knots are placed at appropriate quantiles of data. The best performer in each row is marked in bold.



Figure 4: The figure shows the effects of different components of some of the additive models explained in Table 5.



Figure 5: The figure shows the effects of different components of some of the additive models presented in Table 6.

The models presented in Table 5 and Figure 4 are now extended to be nonlinear functions. There are very few observations at high absolute values, and this results in some quite large crossings. E.g. if the linear functions given above are replaced with spline basis functions, then the worst case crossing has a value of -2847. Therefore values in the tail of the distribution are removed by setting all values above the 95% empirical quantile equal to the 95% empirical quantile and all values below the 5% empirical quantile equal to the 5% empirical quantile.

The result of this is given in Table 6 and Figure 5. The table confirms the point that all three forecasts have to be considered and that we then get a quite large improvement compared to the models with the risk index. The performance was better, however, with the linear hypothesis on the differences.

As has been discussed above, information seems to be reused as the

Model	28	29	30	31	32	33	34
df p_c	5	5	5	5	5	5	5
df $p_{DWD} - p_c$	5	0	0	5	5	0	5
df $p_{HIR} - p_c$	0	5	0	5	0	5	5
df $p_{MM5} - p_c$	0	0	5	0	5	5	5
Below 25%	22.7	22.8	21.6	25.1	23.5	23.3	25.6
Below 75%	75.1	78.9	74.4	79.0	79.0	79.3	79.9
Between 25% and 75%	52.5	56.1	52.8	54.0	54.8	56.1	54.4
$ar{ ho}_{0.25}({f r})$	453.8	454.4	454.5	452.3	450.8	453.2	450.3
$ar{ ho}_{0.75}({f r})$	559.3	559.5	556.6	557.9	559.6	558.9	551.6
$\bar{ ho}_{0.25}(\mathbf{r}) + \bar{ ho}_{0.75}(\mathbf{r})$	1013.1	1013.9	1011.2	1010.3	1010.4	1012.2	1001.9
$d_q(p_c)$	0.062	0.070	0.055	0.061	0.050	0.057	0.057
$d_q(\text{hor})$	0.036	0.043	0.031	0.046	0.024	0.040	0.040
$d_q(t)$	0.030	0.036	0.033	0.033	0.031	0.038	0.041
$\sum I(IQR < 0)$	42	4	47	17	38	17	12
$\min(IQR)$	-4.7	-0.28	-24.9	-9.6	-17.7	-19.5	-32.3
E(IQR IQR < 0)	-2.8	-0.26	-8.4	-4.2	-5.2	-8.7	-15.0
E(IQR IQR > 0)	2311.1	2410.6	2353.2	2424.8	2395.6	2459.6	2425.4
$\tilde{E}(IQR IQR > 0)$	2179.8	2220.9	2191.1	2213.8	2212.4	2332.8	2296.7
SD(IQR IQR > 0)	1841.1	1847.5	1812.7	1863.0	1860.0	1833.1	1795.3
MAD(IQR IQR > 0)	2471.0	2434.4	2398.4	2412.9	2378.8	2454.6	2361.6

Table 6: The table shows different performance parameters for different models. Knots are placed at appropriate quantiles of data. The best performer in each row is marked in bold.

different forecasts are taken into account. A hierarchic structure, where information used in one level is subtracted in the next level, is therefore proposed. In schematic terms this is

1	p_c	p_1	p_2	p_3
2		$p_1 - p_c$	$p_2 - p_c$	$p_3 - p_c$
3			$p_2 - p_1$	$p_3 - p_1$
4				$p_3 - p_2$

The idea is now to use one variable from each level. In the first row this is the combined forecast, in the second row p_1 is chosen as the forecast that gives the best result, etc. Models 28-30 presented in Table 6 give the result we need to choose p_1 . This is the forecast based on MM5 (Model 30). The next rows are chosen in the same way and the results are presented in Figure 6 and Table 7. The performance is about the same for models that include all forecasts.

It is worth noting that the skill score has improved in the model presented in Table 7 at the same time as the reliability has moved away from the required reliability. The same tendency is seen in the reliability distance. This emphasises the difficulty in measuring the performance of quantiles.

This section has discussed different models for quantiles of combined forecasts as proposed in [8]. The conclusion is that the individual forecasts contain information on the uncertainty of these predictions. The analysis also points to the difficulties of measuring performance of quantiles. Since there is no single generally accepted method, a number of different performance parameters are considered, and these do not always point to the same model.

Figure 7 shows local reliability for some of the models presented in this section. The figure shows that at times the overall reliability has very large local deviation from the required reliability. This is especially clear in the direction of the combined forecast.

Section 6 will present some of the static models in an adaptive setting. The models which will be tested in this setting are some of the simple models and some of the best performing models.

Model	30	36	37	38
df p_c	5	5	5	5
df $p_{MM5} - p_c$	5	5	5	5
df $p_{DWD} - p_{MM5}$	0	5	0	0
df $p_{HIR} - p_{MM5}$	0	0	5	5
df $p_{DWD} - p_{HIR}$	0	0	0	5
Below 25%	21.6	24.4	22.7	29.7
Below 75%	74.4	76.2	77.7	78.2
Between 25% and 75%	52.8	51.8	55.3	48.5
$ar{ ho}_{0.25}(\mathbf{r})$	454.5	453.1	452.3	449.2
$ar{ ho}_{0.75}(\mathbf{r})$	556.6	557.8	553.7	550.6
$\bar{ ho}_{0.25}(\mathbf{r}) + \bar{ ho}_{0.75}(\mathbf{r})$	1011.2	1010.9	1006.1	999.8
$d_q(p_c)$	0.055	0.054	0.052	0.079
$d_q(hor)$	0.031	0.026	0.029	0.046
$d_q(t)$	0.033	0.034	0.030	0.047
$\sum I(IQR < 0)$	47	36	43	7
$\min(IQR)$	-24.9	-5.0	-52.1	-28.3
E(IQR IQR < 0)	-8.4	-3.0	-16.7	-9.5
E(IQR IQR > 0)	2353.2	2356.8	2435.9	2308.7
$\tilde{E}(IQR IQR > 0)$	2191.1	2161.4	2236.0	2147.0
SD(IQR IQR > 0)	1812.7	1806.4	1866.6	1752.5
MAD(IQR IQR > 0)	2398.4	2317.2	2450.7	2319.2

Table 7: The table shows different performance parameters for different models. Knots are placed at appropriate quantiles of data. The best performer in each row is marked in bold.



Figure 6: The figure shows the effects of different components of some of the additive models presented in Table 7.



Figure 7: The figure shows local reliability in the direction of forecasted power, horizon and time for some of the models presented in this section.

6 Time-Adaptive Models

The time-adaptive procedure used here is presented in [5] and [7] where a description of the algorithms is given along with an analysis of a data set from Tunø wind power plant. [6] give a technical description of the algorithms, and finally [7] outline some of the results from [5].

The adaptive method needs an updating procedure. The one chosen here is the same as used in [5] and [7], where new observations are classified as belonging to some bin and the oldest observation from this bin are then removed. The number of observations allowed in each bin is 300 and the bins are defined by the knots for the spline basis functions in the direction of the combined forecast.

Tables 8 and 9 present the adaptive version of some of the models presented in Section 5. The numbering is the same as in Section 5, such that, e.g. Model 20 becomes Model A20. It is seen that the performance parameters are improved for most of the models. The skill score for the interval has improved for most of the models, but the skill score for the 25% quantile is worse for most models, while the 75% quantile has improved for all models. The conclusion seems to be that models for the 75% quantile should be adaptive while models for the 25% quantile should not be!

The reliability distance has improved for most of the models and for most of the variables. The improvements are largest in the direction of the combined forecast. This point is also illustrated in Figure 8 where the local reliability is plotted as a function of the combined forecast, horizon and time for the adaptive versions of the models in Figure 7. by comparing Figure 7 with Figure 8 the improvements are clearly seem.

The performance of the adaptive models is worse with respect to crossings than the static models. For models with many degrees of freedom, the extreme crossings can be very large for the adaptive models.

Sharpness has improved for all models, while resolution becomes worse for all models. The relative improvements for sharpness from the static to the adaptive models are between 5% and 12%. This means that the interval covering the central 50% of data is smaller, while the reliability and skill score improved.

For adaptive models the CPU time used for a step forward is also a performance parameter. Therefore the mean CPU time used for one step in the models is also given here. Not surprisingly the time increases with

Model	A5	A4	A9	A11	A14	A17	A20
df	6	7	7	7	11	16	21
Below 25%	22.0	22.8	22.0	22.7	25.5	26.0	25.6
Below 75%	73.4	73.1	73.2	73.7	73.5	75.1	73.8
Between 25% and 75%	51.4	50.5	51.5	51.5	49.3	49.5	48.6
Skill 25%	454.4	457.8	457.4	456.1	459.0	461.4	463.2
Skill 75%	546.2	546.0	543.5	544.5	549.0	547.0	543.5
Skill Interval	1000.6	1003.7	1000.9	1000.7	1008.0	1008.4	1006.7
dq p_c	0.037	0.038	0.039	0.036	0.030	0.028	0.026
dq hor	0.036	0.034	0.036	0.030	0.032	0.030	0.049
dq t	0.032	0.038	0.040	0.039	0.024	0.020	0.032
sum(IQR < 0)	33	34	52	48	57	44	75
$\min(IQR)$	-1.8	-20.5	-47.8	-54.1	-97.2	-17.5	-479.1
mean(IQR < 0)	-0.8	-7.7	-14.4	-12.7	-4.2	-4.4	-25.2
$\mathrm{mean}(\mathrm{IQR})$	2158.1	2158.7	2175.7	2168.9	2161.9	2103.6	2083.3
median(IQR)	2110.3	2110.6	2100.6	2114.0	2022.9	1973.4	1897.7
$\rm sd(IQR)$	1648.9	1639.0	1626.9	1617.5	1614.2	1562.5	1533.3
$\mathrm{mad}(\mathrm{IQR})$	2062.8	2055.3	2037.4	2031.5	2022.9	1930.6	1940.5
Time 25%	0.024	0.036	0.035	0.032	0.112	0.174	0.222
Time 75%	0.017	0.023	0.021	0.021	0.035	0.063	0.130

Table 8: The table shows different performance parameters for adaptive versions of some of the models presented in section 5. The best performer in each row is given in bold.

the number of degrees of freedom in the models. It is also worth noting that the the 25% quantile models are more time consuming than the 75% quantile models, while the most significant improvements were seen for the 75% quantiles.

7 Conclusion

The conclusion is that input for the combined forecast can be used to explain some of the uncertainty in the quantile models. It is still not clear, however, exactly how this should be done. The best performing model is linear in the differences between the combined forecast and the input forecasts, while the hypothesis would be that the inter-quartile range should increase with the

Model	A27	A34	A35	A36	A37	A38
df	9	21	11	16	16	21
Below 25%	27.3	25.9	23.8	24.4	26.0	26.4
Below 75%	75.4	74.3	73.2	73.0	73.5	74.0
Between 25% and 75%	48.2	48.7	49.5	48.9	47.7	47.7
Skill 25%	453.2	452.6	456.8	456.3	456.7	452.9
Skill 75%	531.5	538.5	550.9	552.1	549.6	542.9
Skill Interval	984.7	991.1	1007.7	1008.4	1006.2	995.8
dq p_c	0.038	0.028	0.030	0.033	0.030	0.029
dq hor	0.051	0.031	0.023	0.023	0.023	0.029
dq t	0.042	0.026	0.029	0.028	0.030	0.032
sum(IQR < 0)	1	70	44	63	47	17
$\min(\mathrm{IQR})$	-21.1	-230.5	-626.8	-372.4	-428.7	-243.9
mean(IQR < 0)	-21.1	-42.2	-48.8	-34.1	-79.5	-88.0
$\mathrm{mean}(\mathrm{IQR})$	2094.5	2120.1	2173.2	2136.4	2182.8	2084.5
median(IQR)	1909.0	1946.4	2051.2	2026.9	1907.4	1888.5
$\rm sd(IQR)$	1554.5	1584.7	1657.0	1595.0	1676.0	1587.0
$\mathrm{mad}(\mathrm{IQR})$	1971.7	1977.6	2070.3	1992.6	2098.5	1989.5
Time 25%	0.040	0.216	0.085	0.131	0.097	0.152
Time 75%	0.031	0.159	0.037	0.082	0.078	0.144

Table 9: The table shows different performance parameters for adaptive versions of some of the models presented in section 5. The best performer in each row is given in bold.



Figure 8: The figure shows local reliability in the direction of forecasted power, horizon and time for some of the adaptive models presented in Table 8 and 9.

distance from zero. However, it does seem that the input forecasts should be used individually rather than through the proposed risk indices.

The adaptive method generally gives good results in the performance parameters. There are big differences however between the two quantiles examined. The 25% quantile models do not improve and most of the models get a little worse w.r.t. skill score, while all 75% quantile models improve by going to an adaptive setting. The reliability measure seems to improve, but this has only been recorded as one common number for both quantiles, and it is therefore not clear if there is a difference between the quantiles.

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